

Using Tutte Paths for Finding Long Cycles in Planar Graphs

Andreas Schmid

August 12, 2019



Introduction

Three Applications for Tutte Paths

Algorithms for finding Tutte Paths



But first... P-Bridges

For a path P in G, a P-bridge J is





But first... P-Bridges

For a path P in G, a P-bridge J is a component K of $G \setminus V(P)$





But first... P-Bridges

For a path P in G, a P-bridge J is

- a component K of $G \setminus V(P)$
- plus the edges connecting K to P and their end-vertices (attachments).





Tutte paths - Definition

Let *G* be a 2-connected plane graph with outer face C_G . Then a path *T* is called a **Tutte path** if:

- every *T*-bridge has at most three attachments and
- any *T*-bridge containing an edge of C_G has exactly two attachments (outer bridges).



Tutte paths - Definition

Let *G* be a 2-connected plane graph with outer face C_G . Then a path *T* is called a **Tutte path** if:

- every *T*-bridge has at most three attachments and
- any *T*-bridge containing an edge of C_G has exactly two attachments (outer bridges).

Given endvertices x and y and intermediate edge α , let $x - \alpha - y$ path denote a Tutte path from x to y through α .



Tutte Paths - Example





Using Tutte Paths for Finding Long Cycles in Planar Graphs Andreas Schmid

5/17 August 12, 2019

Tutte paths! What are they good for?



Tutte paths! What are they good for?

Often used to show Hamiltonicity of a graph class:

- 4-connected planar graphs [Tutte56].
- 4-connected projective planar graphs [Thomas94].
- 5-connected toroidal graphs [Thomas97].



Tutte paths! What are they good for?

Often used to show Hamiltonicity of a graph class:

- 4-connected planar graphs [Tutte56].
- 4-connected projective planar graphs [Thomas94].
- 5-connected toroidal graphs [Thomas97].

Or to make even stronger statements:

- 4-connected planar graphs are Hamiltonian-connected [Thomassen83].
- 4-connected planar graphs are 2-edge Hamiltonian-connected [Ozeki2014].
- 4-connected projective planar graphs are Hamiltonian-connected [Kawarabayaschi2015].



Big open question: Which 3-connected planar graphs are Hamiltonian?



Big open question: Which 3-connected planar graphs are Hamiltonian?





Big open question: Which 3-connected planar graphs are Hamiltonian?



■ If *G* has no internal 3-separator [Thomassen83].



Big open question: Which 3-connected planar graphs are Hamiltonian?



If *G* has no internal 3-separator [Thomassen83].

If G has at most three 3-separators [Brinkmann2016].

















Aalto University School of Science

Also used to show relaxations of Hamiltonicity:



Also used to show relaxations of Hamiltonicity:

A cycle of length at least ⁵⁽ⁿ⁺²⁾/₈ in essentially 4-connected planar graphs [Fabrici18].



Also used to show relaxations of Hamiltonicity:

- A cycle of length at least ⁵⁽ⁿ⁺²⁾/₈ in essentially 4-connected planar graphs [Fabrici18].
- Every circuit graph contains a closed 2-walk [Gao95].



Also used to show relaxations of Hamiltonicity:

- A cycle of length at least ⁵⁽ⁿ⁺²⁾/₈ in essentially 4-connected planar graphs [Fabrici18].
- Every circuit graph contains a closed 2-walk [Gao95].
- Circuit graphs always have a 3-tree with few degree three vertices [Nakamoto2009].



















Essentially 4-connected planar graphs





Essentially 4-connected planar graphs





Essentially 4-connected planar graphs













Using Tutte Paths for Finding Long Cycles in Planar Graphs Andreas Schmid A

12/17 August 12, 2019













Using Tutte Paths for Finding Long Cycles in Planar Graphs Andreas Schmid Au

12/17 August 12, 2019







 Decompose the graph into blocks.





- Decompose the graph into blocks.
- Recurse on block B to compute P.





- Decompose the graph into blocks.
- Recurse on block B to compute P.
- Construct subgraph F.





- Decompose the graph into blocks.
- Recurse on block B to compute P.
- Construct subgraph *F*.
- Recurse on F to compute Q.





- Decompose the graph into blocks.
- Recurse on block B to compute P.
- Construct subgraph *F*.
- Recurse on F to compute Q.



 Decompose the graph into blocks.







- Decompose the graph into blocks.
- We modify a block B to B'. depending on its 2-separators



Using Tutte Paths for Finding Long Cycles in Planar Graphs
Andreas Schmid

14/17 August 12, 2019



- Decompose the graph into blocks.
- We modify a block *B* to *B'*. depending on its 2-separators
- Recurse on B' to compute
 P.





- Decompose the graph into blocks.
- We modify a block *B* to *B'*.
 depending on its
 2-separators
- Recurse on *B*' to compute *P*.
- If P contains a virtual edge: recurse on split off graph.





- Decompose the graph into blocks.
- We modify a block B to B'. depending on its 2-separators
- Recurse on *B*' to compute *P*.
- If P contains a virtual edge: recurse on split off graph.





- Decompose the graph into blocks.
- We modify a block B to B'. depending on its 2-separators
- Recurse on *B*' to compute *P*.
- If P contains a virtual edge: recurse on split off graph.
- Merge the resulting path

with paths from other



Using Tutte Paths for Finding Long Cycles in Planar Graphs Andreas Schmid

blocks.

14/17 August 12, 2019



• Decomposing *G* into blocks is in O(n).



Running Time

- Decomposing G into blocks is in O(n).
- All critical 2-separators for the incremental computation of P can be found in O(n).



15/17

Running Time

- Decomposing G into blocks is in O(n).
- All critical 2-separators for the incremental computation of P can be found in O(n).
- Our Algorithm does at most O(n) recursions.



15/17

Running Time

- Decomposing G into blocks is in O(n).
- All critical 2-separators for the incremental computation of P can be found in O(n).
- Our Algorithm does at most O(n) recursions.

Therefore:

Theorem

Let G be a 2-connected plane graph and let $x, y \in V(G)$ and $\alpha \in E(G)$. A $x - \alpha - y$ path in G can be found in $O(n^2)$ time.



Tutte Paths in Linear Time

In ICALP'19, Biedl and Kindermann gave the first linear time algorithm

Based on decomposing the graph into 3-connected subgraphs.



Tutte Paths in Linear Time

In ICALP'19, Biedl and Kindermann gave the first linear time algorithm

- Based on decomposing the graph into 3-connected subgraphs.
- Both end-vertices have to lie on the outer face.
- The authors say this cannot be generalized for arbitrary end-vertex position.



16/17

Future Work

- Find more applications...
- Improve the running time
 - Can our algorithm be improved to O(n) running time?



Future Work

- Find more applications...
- Improve the running time
 - Can our algorithm be improved to O(n) running time?
- Find an algorithm for other variants of Tutte paths (for example in circuit graphs [Jackson2002]).



Future Work

- Find more applications...
- Improve the running time
 - Can our algorithm be improved to O(n) running time?
- Find an algorithm for other variants of Tutte paths (for example in circuit graphs [Jackson2002]).

Thank You! Questions?

